Distributional Impacts of Dynamic Responses to Climate Policy in the Electricity Industry

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Research Question & Motivation

How does a cap-and-trade program for greenhouses gases impact the distribution of local air pollution?

ENVIRONMENTAL JUSTICE V. CAP-AND-TRADE

Tapped - Feb 28, 2008

In a cap-and-trade system, poor communities, where polluting plants are ... But the EJ groups in California are taking a hard line: "[O]ur demands ... concerns of the EJ groups regarding pollution trading, like possible hot spots, ...



Do environmental justice groups have a legitimate beef with Grist Magazine - Apr 5, 2011 Environmental justice groups' beef with emission trading in California goes ... It may be that California should have passed command-and-control ... that cap-and-trade systems do not create hotsports or exacerbate inequality.



Cap-and-trade? Not so great if you are black or brown Grist - Sep 16, 2016

Environmental justice advocates have long warned that ... A preliminary report on California's cap-and-trade program shows they just might be right. ... California EJ groups issued a declaration against cap-and-trade back in 2008. The new report – by researchers at UC Berkeley, the University of Southern

Expected responses of the electricity industry to cap-and-trade

1. Redistribution of market share to low-emission intensity units

 \rightarrow change in unit capacity factors

2. Decrease in carbon emissions intensities

 \rightarrow investments to improve to unit efficiency (reduce heat rate) in natural gas dominated markets; fuel switching in markets with coal

Model and identification

Firms, as single-agents, makes two decisions in each period:

- Decides whether to operate \rightarrow determines production quantity
- \blacktriangleright Decides whether invest to improve its efficiency \rightarrow determines next period heat rate
- Per period profits constructed a function of state variables including lagged operating state and investment decision

Identification of unknown structural parameters:

- Start-up costs are identified by the willingness of the generator to operate in two states that differ only in last period operating decision
- Investment costs are identified by difference in heat rates across different marginal costs (carbon prices)

Estimation approach

Two-step estimation approach

Use Bajari, Benkard, and Levin (2007) approach to estimate policy functions for production and investment decisions; develop approximation of electricity price paths in counterfactuals.

Data

- Prices: Hourly wholesale electricity prices from CAISO; carbon allowance prices: ICE; fuel input prices: federal reporting requirements and Bloomberg coal/natural gas spot prices
- Production quantities: Unit-specific hourly electricity output from CEMS
- Emission quantities: Hourly emissions of NO_x, SO₂, CO₂ from CEMS
- Unit characteristics: various EIA reporting requirements

Average profits per hour, 2012-2016



Carbon prices over time



Input fuel prices over time



Capacity factors for sample month (Sept.), 2012 - 2016



Unit efficiency by month for example units



Heat rates for sample month (Sept.), 2012 - 2016



Contributions of this work

- 1. Develop a dynamic model of electric generating behavior that includes both production and investment.
- 2. Simulate counterfactual outcomes of redistribution and investment in efficiency under different GHG policy scenarios (e.g. a more stringent policy with higher prices, a command and control approach).
- 3. Map market outcomes across carbon policy scenarios to local air quality outcomes and damages to human health (leveraging epidemiological work and/or AP2 (APEEP) model).

Per Period Profits

 $\pi_t(q(a_{it}), P_t, C_{it}, \Gamma_{it}, L_{it}) =$

$$\begin{aligned} q_{it}(P_t - C_t(hr_{it}, mc_f, e_g, \tau_t)) - \Gamma(z_{it}, v_{it}; \gamma_i), & a_{it} = 1, L_{it} = 1\\ q_{it}(P_t - C_t(hr_{it}, mc_f, e_g, \tau_t)) - \Gamma(z_{it}, v_{it}; \gamma_i) - start_i, & a_{it} = 1, L_{it} = 0\\ 0, & a_{it} = 0\\ (1) \end{aligned}$$

- start_i: start-up costs incurred when turning on after lagged operating state L_{it} = a_{it-1} = 0
- P_t: exogenous hourly price (to be discussed)
- C_t(·): marginal cost function:

$$C_t = hr_{it} * mc_f + hr_{it} * e_f \tau_t \tag{2}$$

- hr_{it}: heat rate, mc_f: marginal costs of fuel, e_g: emissions rate of fuel, τ_t: GHG emissions permit price
- $\Gamma_t(\cdot)$: cost of investment (previous slide)

Firm Decision 1: Operation (production) choice

Firm i = 1, ..., N makes operating decision $a_{it} \in \{0, 1\}$ in each hour t which determines q_{it}

$$q_{it} = q_{max,i} \text{ if } P_t \ge C_{it} \text{ and } a_{it} = 1$$

$$q_{it} = q_{min,i} \text{ if } P_t < C_{it} \text{ and } a_{it} = 1$$
(3)

- q_{max(min),i}: unit-specific production constraint
- P_t: wholesale electricity price in hour t
- C_{it}: marginal cost of electricity

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Firm Decision 2: Investment choice

When $a_{it} = 1$, firm makes an investment decisions $z_{it} \in \mathcal{R}^+$, which improves the efficiency (reduces the heat rate) hr_{it+1} with cost $\Gamma(\cdot)$

$$hr_{it+1} = hr_{it}(1+\delta) - z_{it}$$

$$\Gamma(z_{it}, hr_{it}, \gamma_i, v_{it}) = 1(z_{it} > 0)(\gamma_{g(i)1} + \gamma_{g(i)2} \frac{z_{it}}{hr_{it}} + v_{it})$$
(4)

- δ: depreciation rate
- $\gamma_{g(i)1}, \gamma_{g(i)2}$: fixed and variable costs of investment for technology group g(i)
- v_{it}: stochastic shock to investment costs

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State Transitions and Timing

Transitions

- $H_{t+1} = H_t + 1 1(H_t = 24) * 24$
- $\blacktriangleright L_{t+1} = a_t$

$$hr_{t+1} = hr_t(1+\delta) - z_t$$

- ▶ $P_{t+1} = F(P_{t+1}|P_t, H_t)$ AR (1), beliefs consistent with equilibrium prices
- ► $\tau_{t+1} = T(\tau_{t+1}|\tau_t, H_t)$ or $T(\tau_{t+1}|\tau_t, m_t)$ AR(1), beliefs consistent with equilibrium prices

Timing

▶ In period *t*, firm observes P_t , H_t , L_t , hr_t , τ_t , ϵ_t , and v_t develops expectations about P_{t+1} and τ_{t+1} , decides whether to operate, and conditional on $a_t = 1$, decides z_t .

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Intertemporal Problem

Firms choose a_t and z_t to maximize the sum of discounted profits:

$$V(s_{t}) = \max_{a_{t}, z_{t}} \sum_{j=0}^{\infty} \beta^{j} \Pi(a_{t+j}, z_{t+j}, s_{t+j} | a_{t+j}, z_{t+j}, s_{t})$$

$$s_{t} = \{x_{t}; e_{t}\} = \{P_{t}, H_{t}, L_{t}, hr_{t}, \tau_{t}; \epsilon(a_{t}), v_{t}\}$$
(5)

> The Bellman equation for this dynamic programming problem is:

$$V(s_t) = \max_{a_t, z_t} \{ \Pi(s_t, a_t, z_t) + \beta E[V(s_{t+1})|a_t, z_t, s_t]$$

$$E[V(s_{t+1})|a_t, z_t, s_t] =$$
(6)

$$\int V(P_{t+1}, H_{t+1}, L_{t+1}, hr_{t+1}, \tau_{t+1}; \epsilon_{t+1}(a_{t+1}), v_{t+1}|P_t, H_t, L_t, hr_t, \tau_t)[...] dP(\epsilon_{t+1}(a_{t+1}), v_{t+1}, P_{t+1}, \tau_{t+1})$$
(7)

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